



KI

ABSICHERUNG

Safe AI for Automated Driving

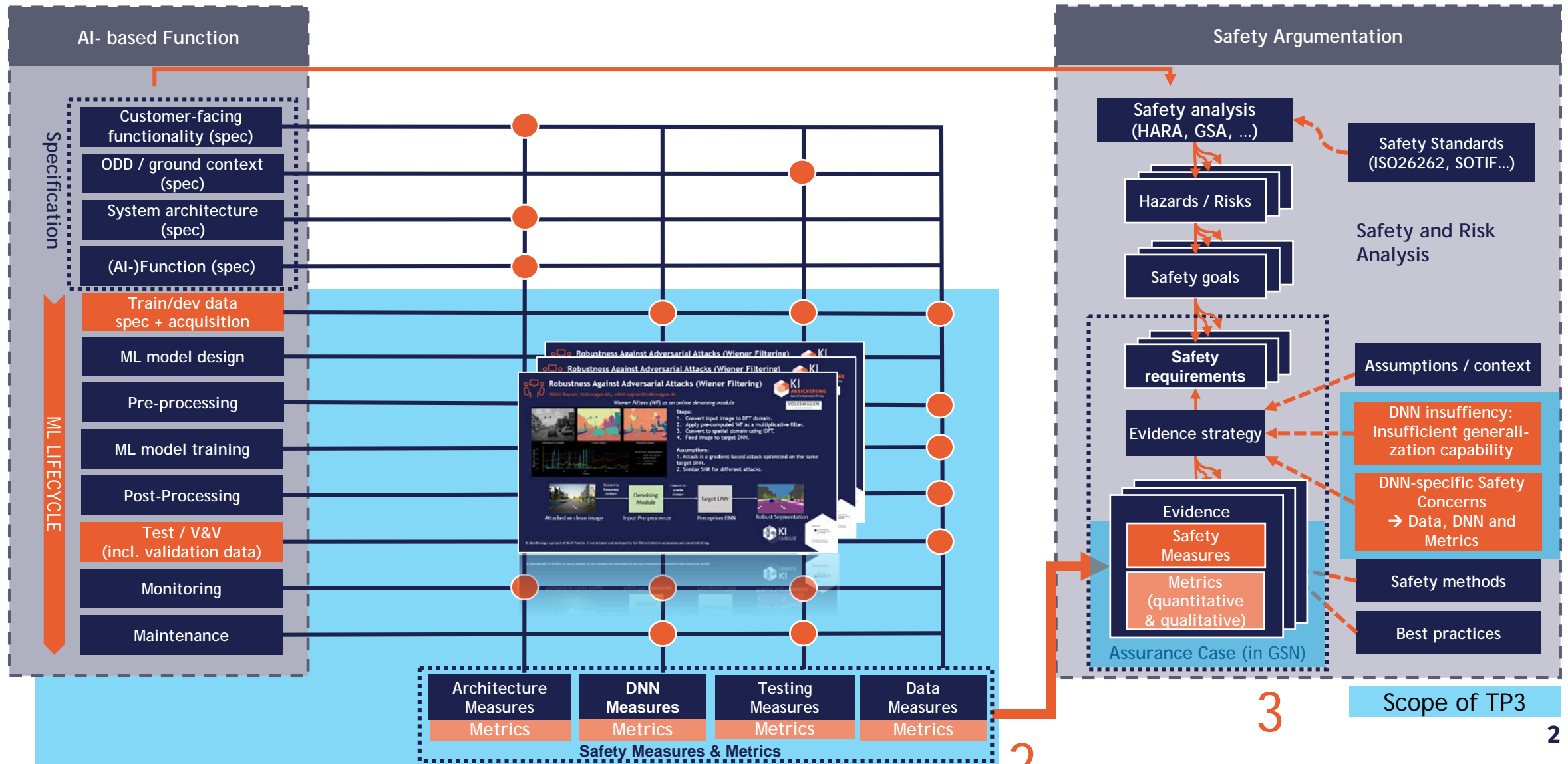
11th March 2021, Online, Interim Presentation

Developing and evaluating measures and methods for the verification of the AI function

Dr. Fabian Hüger, Volkswagen AG



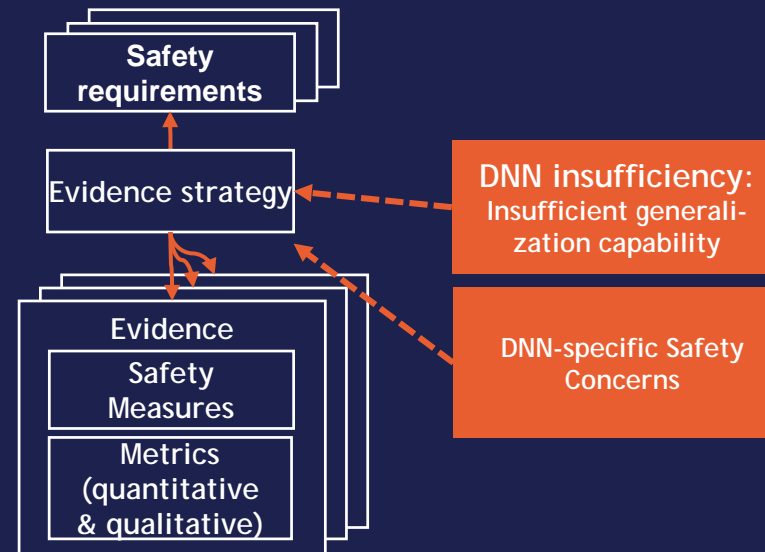
Methods and Measures in context of the KI Absicherung Big Picture





1

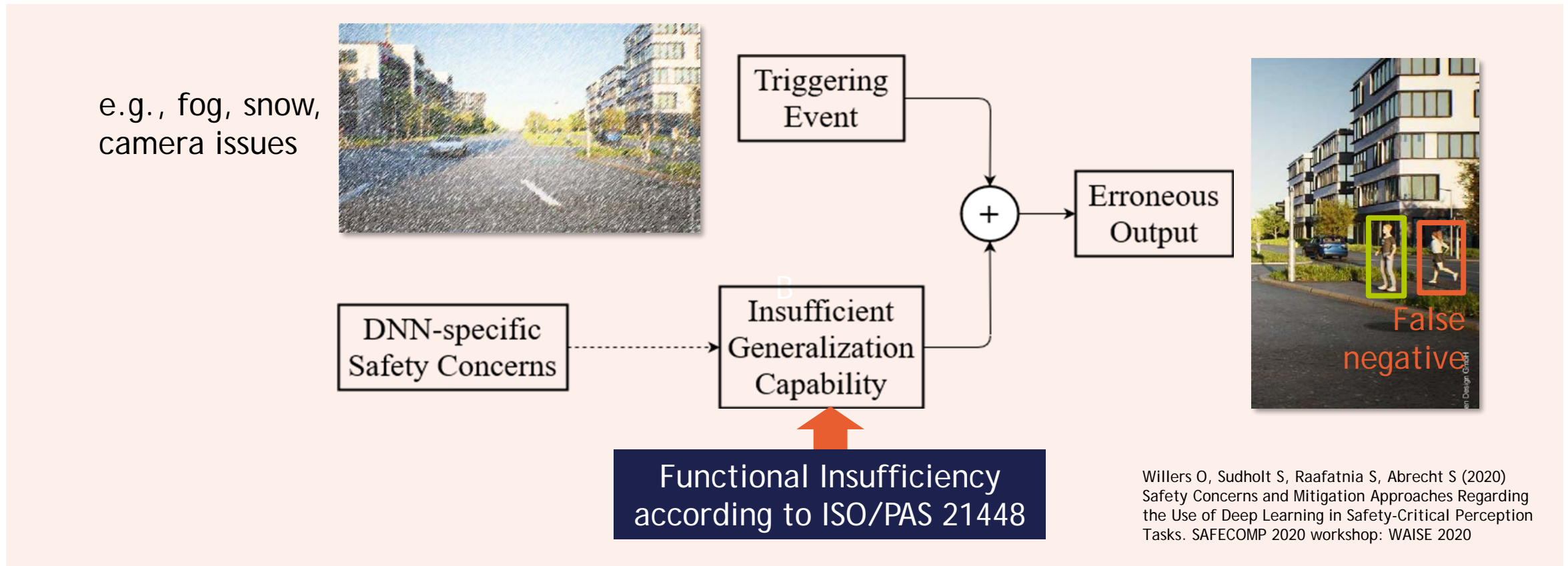
DNN-specific Safety Concerns





DNN-specific Safety Concerns (1/2)

We define **DNN-specific Safety Concerns (SCs)** as underlying issues of DNN-based perception which may negatively affect the safety of a system.





Work-in-progress

Based on:

O. Willers, S. Sudholt, S. Raafatnia, S. Abrecht: Safety Concerns and Mitigation Approaches Regarding the Use of Deep Learning in Safety-Critical Perception Tasks

T. Sämman, P. Schlicht, F. Hüger: Strategy to Increase the Safety of a DNN-based Perception for HAD Systems

G. Schwalbe, B. Knie, T. Sämman, T. Dobberphul, L. Gaueroth, S., V. Rocco: Structuring the Safety Argumentation for Deep Neural Network Based Perception in Automotive Applications

Functional Insufficiencies

DNN-characteristics-related concerns

Data-related concerns

Metric-related concerns

FI-1 INSUFFICIENT GENERALIZATION CAPABILITY

Wrong outputs by an AI-based function that was trained on a limited database. Erroneous input to output mapping or wrong approximation.

SC-1.1 UNRELIABLE CONFIDENCE INFORMATION

DNNs tend to be overconfident in their predictions under certain conditions or in general outputting unreliable confidence information.

SC-1.2 BRITTLINESS OF DNNs

Non-robustness against common perturbations such as noise or certain weather conditions as well as targeted perturbations known as adversarial examples

SC-1.2.1 LACK OF TEMPORAL STABILITY

Detection results rapidly changing in time whereas little change occurs in the ground truth

SC-1.3 INCOMPREHENSIBLE BEHAVIOUR

Inability to explain exactly how DNNs come to a decision.

SC-1.4 INSUFFICIENT PLAUSIBILITY

AI based functions usually lack basic plausibility checks, which are intended to identify detections of the perception function that violate physical laws.

SC-2.1 DATA DISTRIBUTION IS NOT A GOOD APPROXIMATION OF REAL WORLD

The distribution of data used in the development should be a valid approximation of the ODD in the real world.

SC-2.2 INADEQUATE SEPARATION OF TEST AND TRAINING DATA

Test data might be correlated to training data which might induce overfitting on test data.

Technologies Abschnitten

SC-2.3 DEPENDENCE ON LABELLING QUALITY

Labelling quality can directly affect the resulting model performance. Moreover, due to missing labelling quality, evaluation results might be misleading.

SC-2.3.1 MISSING LABEL DETAILS OR META-LABELS

Missing meta-labels or label details possibly leads to improper data selection or insufficient training objectives.

SC-2.4 SPECIFICATION OF THE ODD

An incomplete or incorrect ODD specification leads to incomplete data records for training and testing.

SC-2.5 DISTRIBUTIONAL SHIFT OVER TIME

A DNN is trained and tested at a certain point in time. Changes will occur naturally and therefore can potentially harm the performance of DNNs.

SC-2.6 UNKNOWN BEHAVIOUR IN RARE CRITICAL SITUATIONS

The long tail problem describes the fact that there exists an enormous amount of possibly safety-critical street scenes that have a low occurrence probability.

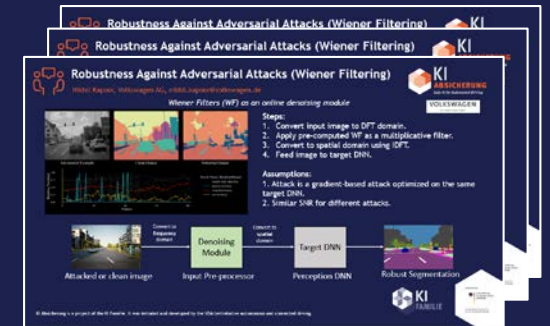
SC-3.1 SAFETY-AWARE METRICS

Some state-of-the-art metrics only evaluate the average performance of DNNs. Safety-aware metrics are required to sophisticatedly evaluate the performance of DNNs.



2

Exemplary Methods and Measures



Inspect, Understand, Overcome: A Survey of Practical Methods for AI Safety

Initial State-of-Research Report

Sebastian Henken¹, Stephanie Abrecht², Maram Akila³, Andreas Bar⁴, Felix Brockherde⁵, Patrick Felder⁶, Timo Gackert⁷, Ahmad Hammami⁸, Anselm Hahn⁹, Nikhil Kapoor¹⁰, Jonas Leibler¹¹, Pavlitskaya¹², Rosenzweig¹³, Marlene Schmitt¹⁴, Elena Schulz¹⁵, Gernot Schuster¹⁶, Michael V. Hoffmann¹⁷

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Mechanisms Catalogue

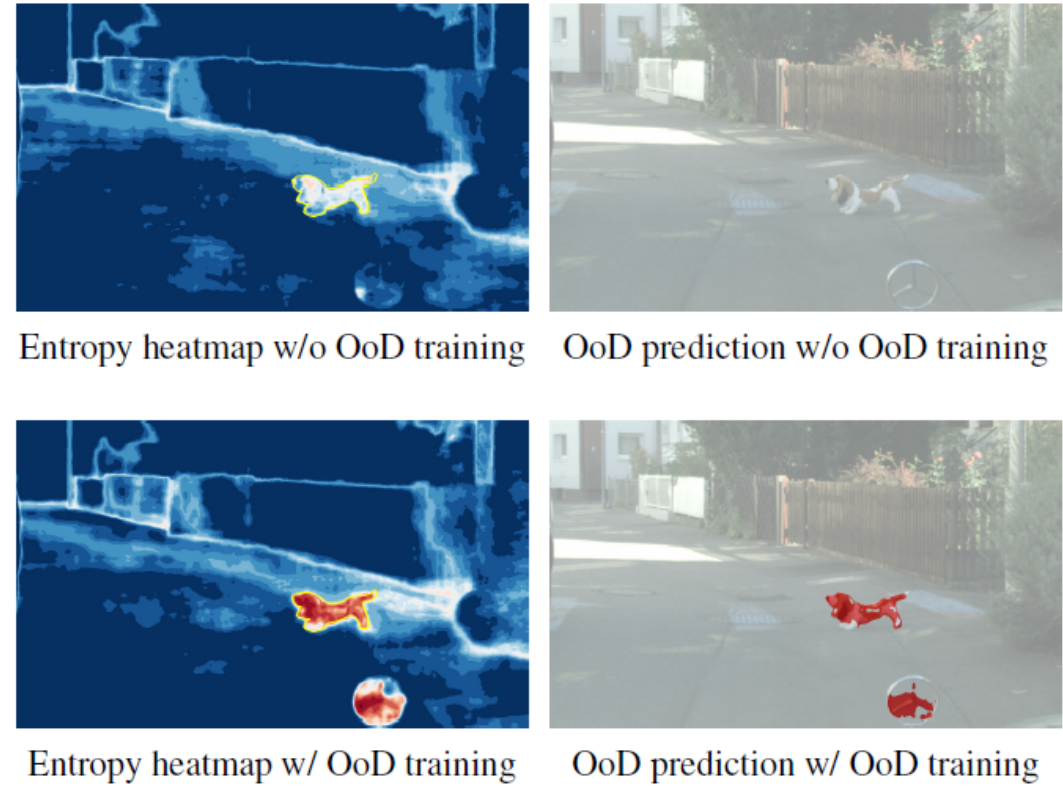
Survey available at www.ki-absicherung-projekt.de/

Entropy Maximization and Meta Classification for Out-of-Distribution Detection in Semantic Segmentation

Addressed Safety Concerns:
Unreliable confidence information

Enforce segmentation networks to output high prediction uncertainty on **Out-of-Distribution inputs** by means of a modified loss function

Figure 2: Comparison of softmax entropy heatmap and OoD prediction mask with our OoD training (*top row*) and without (*bottom row*). The yellow lines in the entropy heatmaps mark the annotation of the OoD object. The OoD object prediction is obtained by simply thresholding on the entropy heatmap (in this example at $t = 0.7$ yielding the red pixels in the OoD prediction masks).



Entropy Maximization and Meta Classification for Out-Of-Distribution Detection in Semantic Segmentation, R Chan et al., arXiv preprint arXiv:2012.06575, 2020

Object Detection Uncertainty based on Gradient Information

Addressed Safety Concerns:
Unreliable confidence information

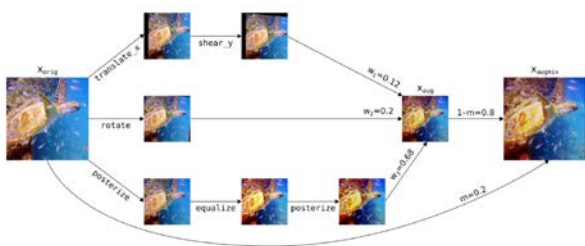
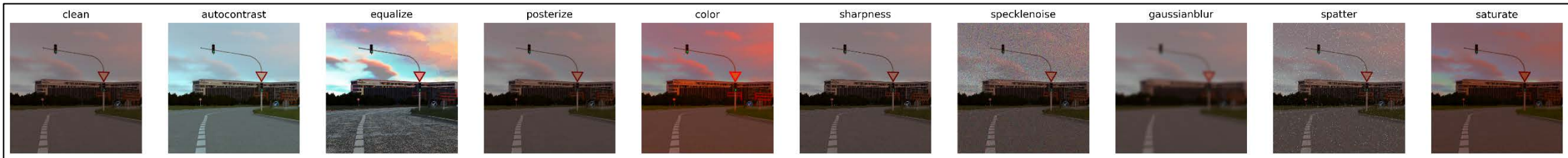


Tackling overconfidence via novel online uncertainty mechanism using gradient information

False Prediction at 0.7 confidence

Augmentation Training (AugMix)

Addressed Safety Concerns:
Brittleness of DNNs



Combined using AugMix

- + Improved robustness
- + Improved generalization
- + Data efficient augmentation strategy

AUGMIX: A SIMPLE DATA PROCESSING METHOD TO IMPROVE ROBUSTNESS AND UNCERTAINTY

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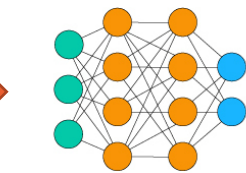
Barret Zoph
Google
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Justin Gilmer
Google
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DeepMind
balaji1n@google.com



Training



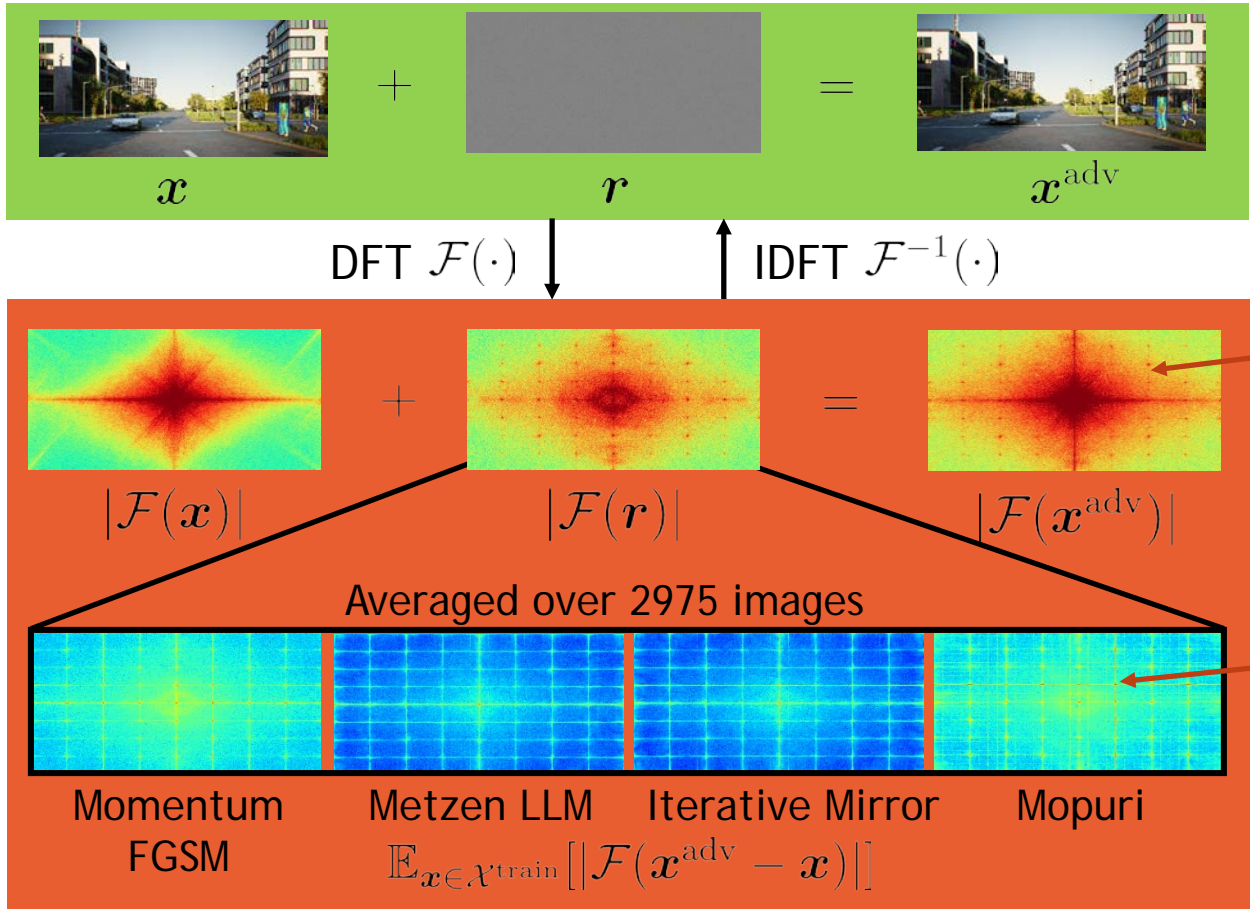
DeepLabv3
ResNet 101
(KIA model by Intel)

Evaluation on *unseen* „real-world“ corruptions

AugMix: A Simple Data Processing Method to Improve Robustness and Uncertainty, D. Hendrycks et al, <https://arxiv.org/abs/1912.02781>

Wiener Filters (WF) as an online denoising module

Addressed Safety Concerns:
Brittleness of DNNs



Adversarial examples are imperceptible in the spatial domain

Strong visible artifacts in the frequency domain

These artifacts are image-type and attack-type independent

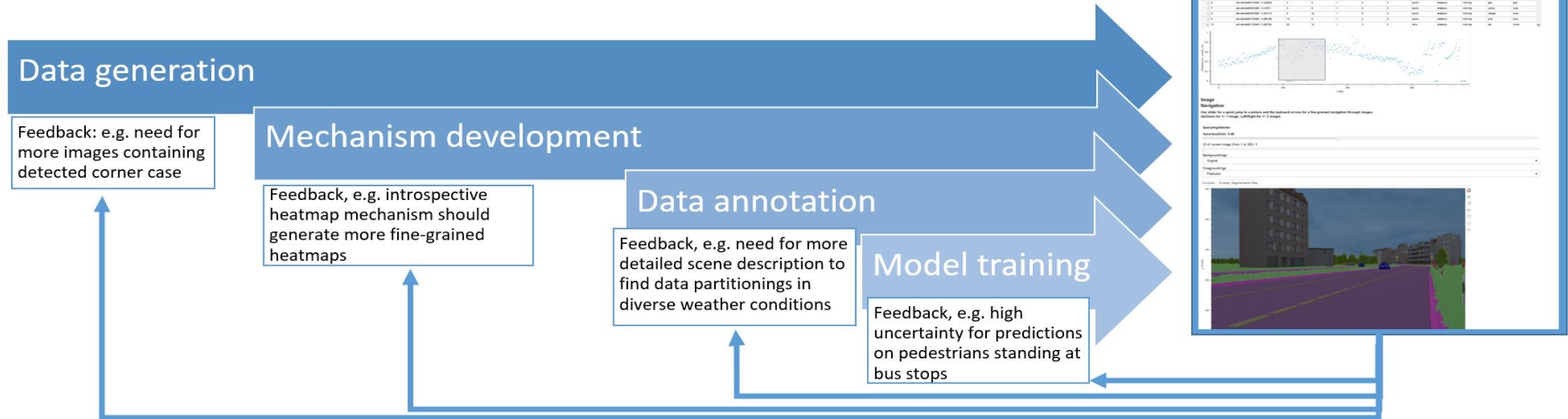
■ Spatial domain
■ Frequency domain

From a Fourier-Domain Perspective on Adversarial Examples to a Wiener Filter Defense for Semantic Segmentation, N. Kapoor et al. <https://arxiv.org/abs/2012.01558>

Semantic Analysis of DNN Predictions with Visual Analytics

Addressed Safety Concerns:
Incomprehensible
Behavior

- Development of a visual interactive interface
 - Inspection of DNN predictions and data sets w.r.t. pre-computed meta data (semantics)
 - Interactive, Modular, Extensible
- Feedback loop between data generation, DNN training and analyses



Heatmap-based Attention Consistency Validation

Addressed Safety Concerns:
Insufficient Plausibility



Detection of implausibilities between detections and attention



Further exemplary mechanisms

- Mixture of Experts
- Domain Randomization in Optimized Dataset Selection
- MC Dropout
- Uncertainties For Anomaly Detection
- Hybrid Learning using Concept Enforcement
- Active Learning
- Adversarial Training
- Hybrid and robustness-focused Compression
- ...

3



Injecting Mechanisms into
the Safety Argumentation:
Evidence Workshops



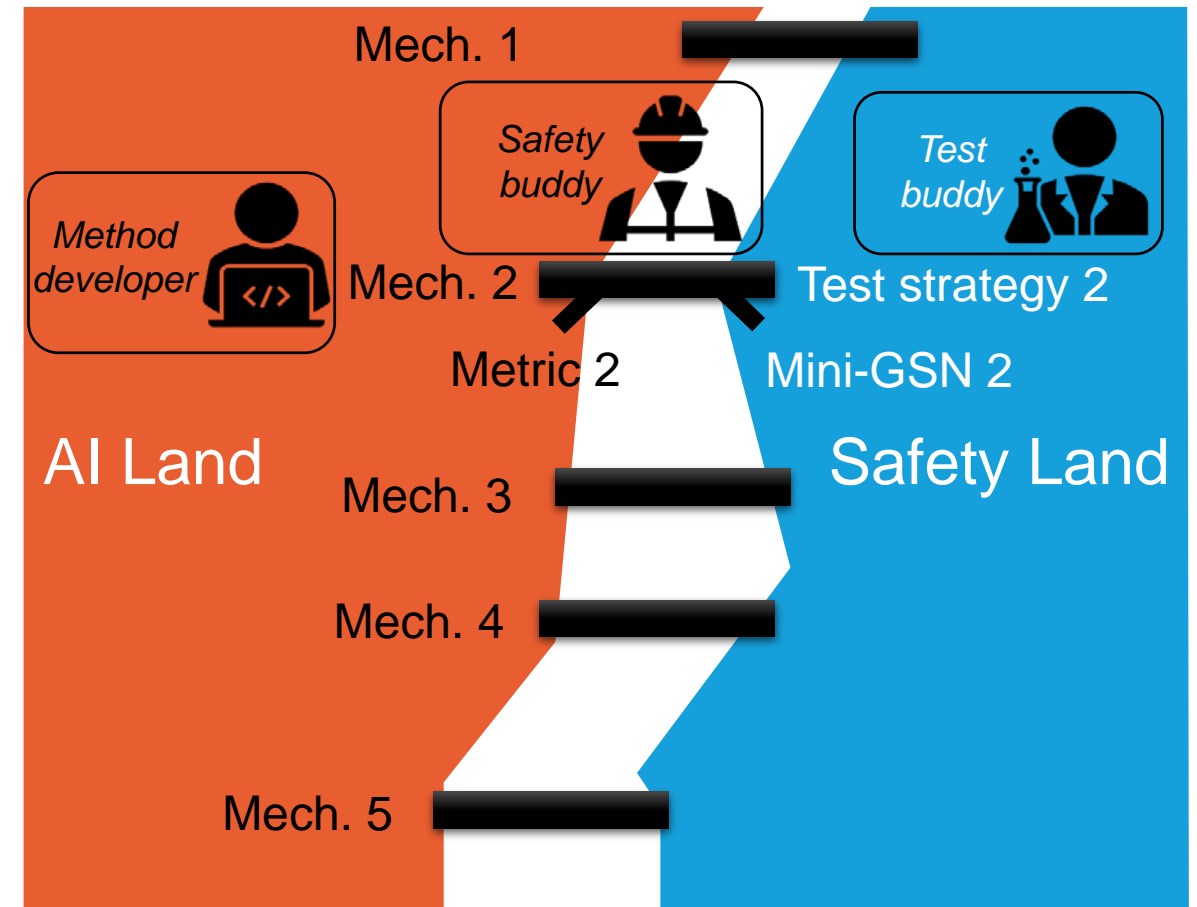
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Evidence workshops from P4

How to build the **big bridge** between AI Land and Safety Land?



Evidence workshops were conducted to streamline and integrate the mechanisms into the safety argumentation in TP4

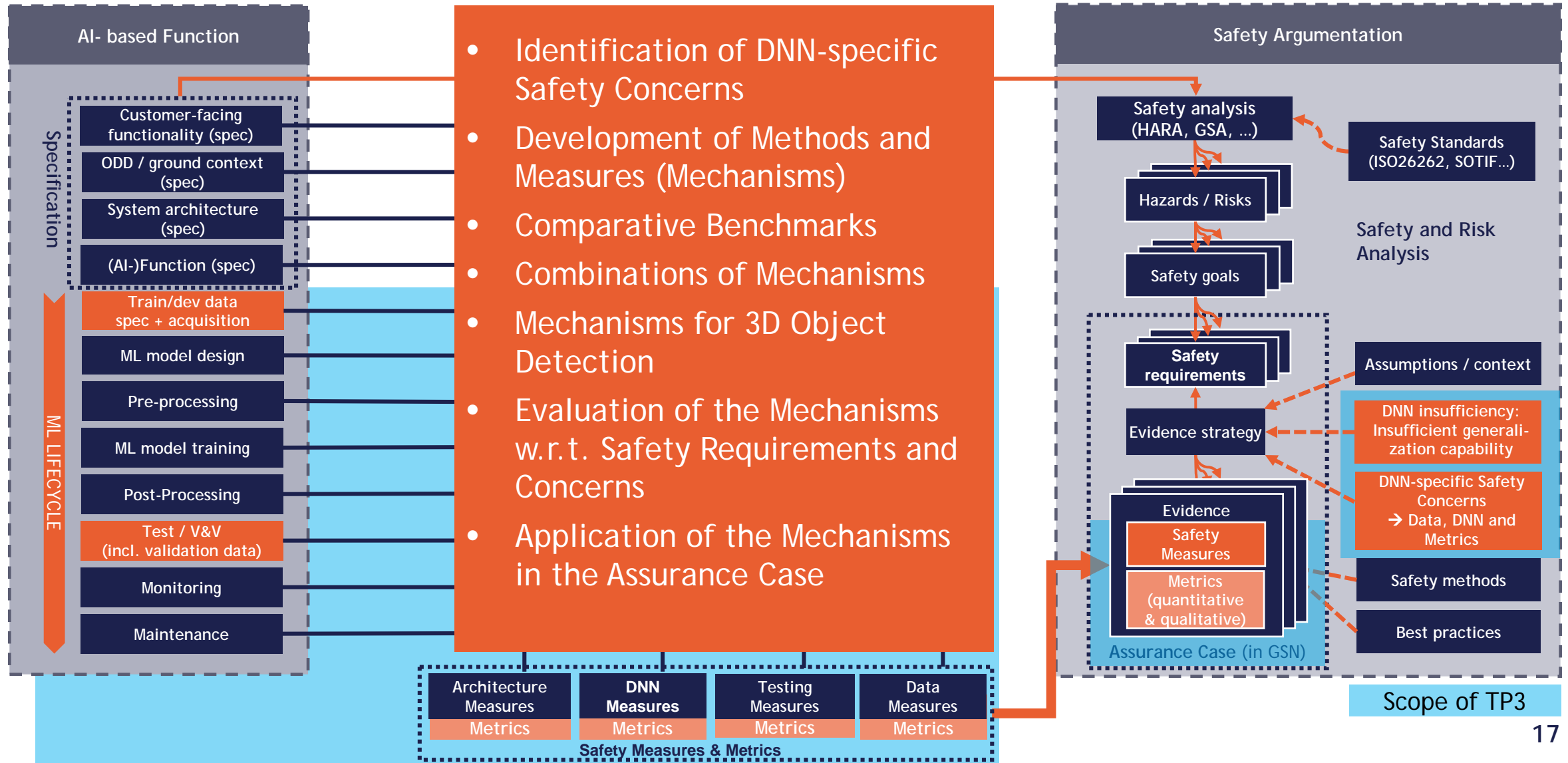




4

Summary & Outlook

Summary and Outlook



SAIAD Workshop 2021



The poster features a dark background with a faint image of a brain. At the top left, it says 'CVPR VIRTUAL JUNE 19-25'. The main title 'SAIAD 2021' is in large white letters. Below it, '3rd Workshop' and 'Safe Artificial Intelligence for Automated Driving' are written. It also mentions 'in conjunction with IEEE Computer Society Conference on Computer Vision and Pattern Recognition (CVPR'2021)'. At the bottom, it says 'Accepted papers will be published in IEEE Xplore!' and 'June 19th-25th virtually'.

Organized by



Invited Speakers



<https://sites.google.com/view/saiad2021>

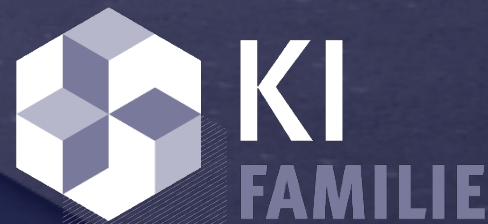
Submission Deadline: March 15, 2021, Anywhere on Earth (UTC-12)



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KI Absicherung ist ein Projekt der KI Familie
und wurde aus der VDA Leitinitiative autonomes
und vernetztes Fahren heraus entwickelt.

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