ABSICHERUNG Safe AI for Automated Driving

October 11 2021, ITS World Congress KI Absicherung

Lydia Gauerhof, Robert Bosch GmbH





Project vision and goals



Making the safety of Al-based function modules for highly automated driving verifiable

KIABSICHERUNG

Safe AI for Automated Driving

Pedestrian detection

Challenge





Methodological and conceptual approach



AI Function-Pedestrian detection





Semantic Segmentation



2D Bounding Box Detection





3D Bounding Box Detection





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Generate synthetic data

ML-Lifecycle-Validation data











Generate synthetic data

Develop methods and measures

Identify, Measure and & Counteract "DNN-specific Safety Concerns"





DNN-specific safety concern:

 False positive / negative: Pedestrian detection is incorrect resp. not robust enough

Method:

• Assessment of uncertainty: Stochastic evaluation of a multitude of model variations (Monte Carlo Dropout)



Counter mechanisms during training or operation

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- Generate synthetic data
- **Develop methods and measures**
- Establish an overall safety argument for the AI function

Specification



Function Environment

System Architecture







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Our Approach: Establishment of a Holistic Safety strategy





AI Specific Evidence-Based Safety Argumentation





Safety measures & metrics & data 2 a a a



- Generate synthetic data
- **Develop methods and measures**
- Establish an overall safety argument for the AI function
- Communicate the results



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www.ki-absicherung-projekt.de 🈏 @KI_Familie in KI Familie



Federal Ministry for Economic Affairs and Energy

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